

Website

<http://loris-7.ddns.comp.nus.edu.sg/~project/s2/beta/>

Motivation

- Shape analysis is crucial for proving memory safety and is a precursor to supporting functional correctness on heap manipulating programs.
- Inferring shapes describing abstractions for data structures used by each method is challenging to automatic program verifiers.
- Shape synthesis for arbitrary data structures to support recursive procedures is even more challenging.

Main Ideas

- Grounded on abduction rather than deduction.
- Distinguish unknown pre-predicates in pre-conditions, from unknown post-predicates in post-condition; since the former may be strengthened, while the latter may be weakened.
- Support *heap guard* mechanism for more precise preconditions on heap specification.
- Normalize inferred shape predicates to facilitate the reuse of existing predicates.

Second-Order Bi-Abductive Entailment

Given an antecedent Δ_{ante} and a consequent Δ_{conseq} , the second-order bi-abductive entailment checker constructs both the frame residue Δ_{frame} and a set of relational assumptions of the form $\mathcal{R} = \bigwedge_{i=1}^n (\Delta_{\text{lhs}}^i \Rightarrow \Phi_{\text{rhs}}^i)$ such that:

$$\Delta_{\text{ante}} \vdash \Delta_{\text{conseq}} \rightsquigarrow (\mathcal{R}, \Delta_{\text{frame}})$$

Semantics:

$$\mathcal{R} \wedge \Delta_{\text{ante}} \models \Delta_{\text{conseq}} * \Delta_{\text{frame}}$$

Example: H is an unknown predicate and $x \rightarrow \text{tree}(p, l, r, t)$ is a consequent that ensures x points to an allocated heap, as required for field access.

$$H(x, p, t) * \Delta \vdash x \rightarrow \text{tree}(x_p, l, r, n) \rightsquigarrow (\mathcal{R}_1, \Delta_1)$$

$$\mathcal{R}_1 \equiv H(x, p, t) \Rightarrow x \rightarrow \text{tree}(x_p, l, r, n) * H_p(x_p, p, t) * H_1(l, p, t) * H_r(r, p, t) * H_n(n, p, t)$$

$$\Delta_1 \equiv \Delta * H_p(x_p, p, t) * H_1(l, p, t) * H_r(r, p, t) * H_n(n, p, t)$$

Hoare Rules

$$\vdash \{\Delta_{\text{pre}}\} e \{ \mathcal{R}, \Delta_{\text{post}} \}$$

where \mathcal{R} accumulates the set of relational assumptions generated by the entailment procedure.

Derivation of Shape Predicates

function PRED.SYN(\mathcal{R})

$\Gamma \leftarrow \emptyset$

$\mathcal{R} \leftarrow$ exhaustively apply [Syn-Base] on \mathcal{R}

$\mathcal{R}_{\text{pre}}, \mathcal{R}_{\text{post}} \leftarrow \text{sort-group}(\mathcal{R})$

while $\mathcal{R}_{\text{pre}} \neq \emptyset$ **do**

$\mathcal{U}^{\text{pre}}, \sigma \leftarrow$ pick unknown and select related assumptions in \mathcal{R}_{pre}

$\mathcal{U}_{\text{def}}^{\text{pre}} \leftarrow$ apply [Syn-Case], [Syn-Group-Pre] and [Syn-Pre-Def] on σ

$\mathcal{R}_{\text{pre}}, \mathcal{R}_{\text{post}} \leftarrow$ inline $\mathcal{U}_{\text{def}}^{\text{pre}}$ in $(\mathcal{R}_{\text{pre}} \setminus \sigma)$ and $\mathcal{R}_{\text{post}}$

discharge \mathcal{U}^{pre} obligations

$\Gamma \leftarrow \Gamma \cup \{\mathcal{U}_{\text{def}}^{\text{pre}}\}$

end while

while $\mathcal{R}_{\text{post}} \neq \emptyset$ **do**

$\mathcal{U}^{\text{post}}, \sigma \leftarrow$ pick unknown and select related assumptions in $\mathcal{R}_{\text{post}}$

$\mathcal{U}_{\text{def}}^{\text{post}} \leftarrow$ apply [Syn-Group-Post], [Syn-Post-Def] on σ

discharge $\mathcal{U}^{\text{post}}$ obligations

$\mathcal{R}_{\text{post}} \leftarrow \mathcal{R}_{\text{post}} \setminus \sigma$ $\Gamma \leftarrow \Gamma \cup \{\mathcal{U}_{\text{def}}^{\text{post}}\}$

end while

return Γ

end function

Normalization of Shape Predicates

function PRED.NORM(Γ)

$\Gamma_1 \leftarrow$ process-dangling-and-unused-preds Γ

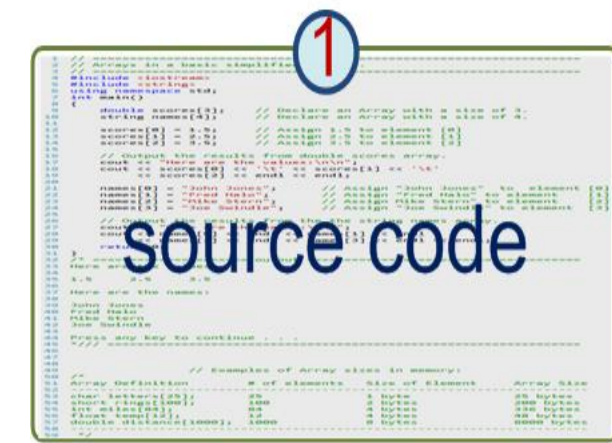
$\Gamma_2 \leftarrow$ eliminate-useless-parameters Γ_1

$\Gamma_3 \leftarrow$ perform-predicate-splitting on Γ_2

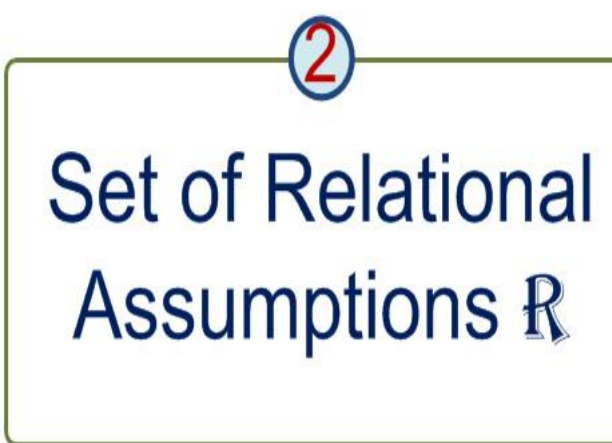
return reuse-predicates Γ_3

end function

The Proposed Method



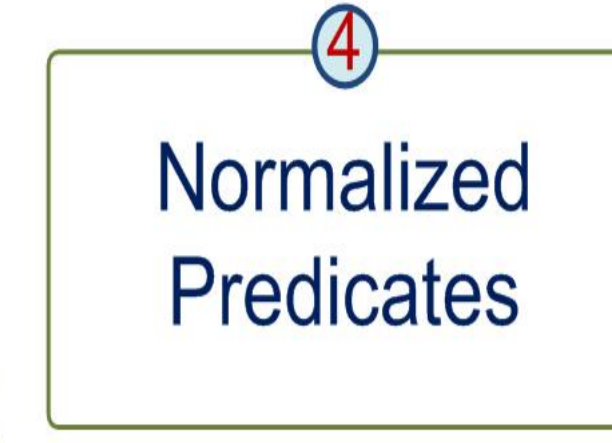
Second-Order Bi-Abductive Entailment



Derivation of Shape Predicates



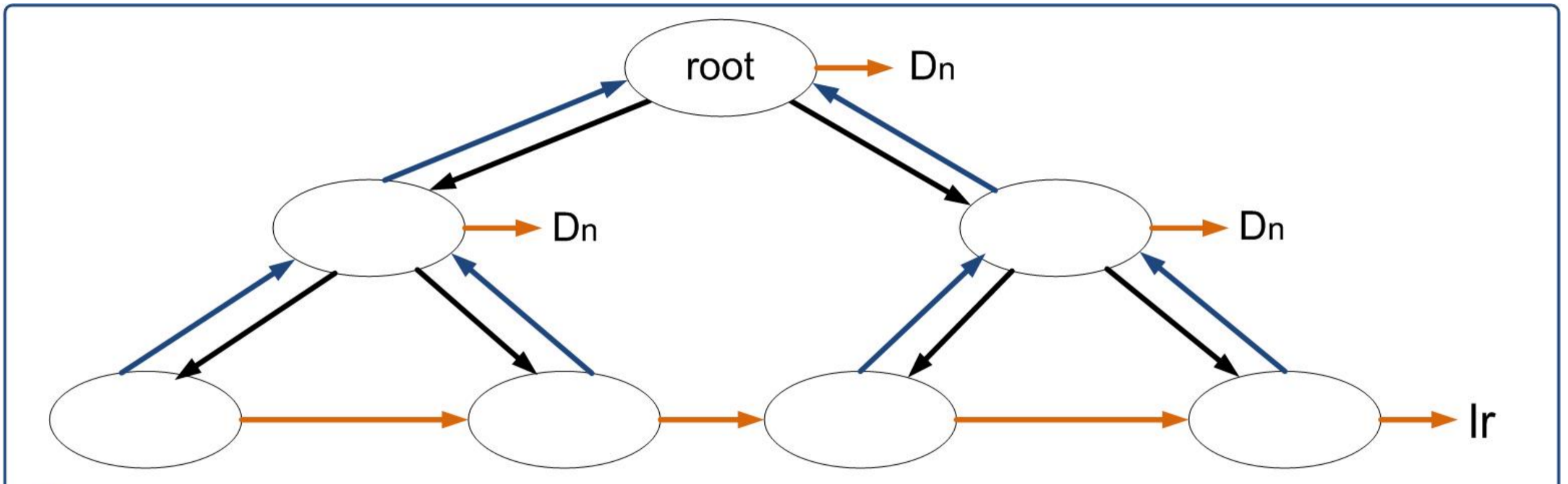
Normalization of Shape Predicates



Motivating Example

```
struct tree { struct tree* parent; struct tree* l; struct tree* r; struct tree* next;
requires H(x,p,t) ensures G(x,p,res,t)
```

```
struct tree* tll(struct tree* x, struct tree* p, struct tree* t)
{
//S1(PRE) : H(x,p,t)
x->parent = p;
//S2(BIND) : x->tree(p,l,r,n)*H1(l,p,t)*Hr(r,p,t)*Hn(n,p,t)*Hp(xp,p,t)
if (x->r=NULL) {
//S3(THEN) : x->tree(p,l,r,n)*H1(l,p,t)*Hr(r,p,t)*Hn(n,p,t)^r=NULL
x->next=t; return x; }
//S6(POST1) : x->tree(p,l,r,t)*H1(l,p,t)*Hr(r,p,t)^r=NULL^res=x
else {
//S4(ELSE) : x->tree(p,l,r,n)*H1(l,p,t)*Hr(r,p,t)*Hn(n,p,t)^r=NULL
struct tree* lm;
//S5(REC-PRE-1) :
lm = tll(x->r, x, t);
//S5(REC-PRE-2) : x->tree(p,l,r,n)*H1(l,p,t)*G(r,x,lm,t)*Hn(n,p,t)^r=NULL
return tll(x->l, x, lm); }
//S7(POST2) : x->tree(p,l,r,n)*G(l,x,res,lm)*G(r,x,lm,t)*Hn(n,p,t)^r=NULL
```



tll: tree with parent pointers, leaves are linked as a list

Relational Assumption	Remark	Entailment
(1) $H(x,p,t) \Rightarrow x \rightarrow \text{tree}(x_p, l, r, n) * H_p(x_p, p, t) * H_1(l, p, t) * H_r(r, p, t) * H_n(n, p, t)$	BIND	$S1 \vdash x \rightarrow \text{tree}(p, l, r, n)$
(2) $H_r(r, p, t) \wedge r \neq \text{NULL} \Rightarrow H(r, x, t) @ x \rightarrow \text{tree}(p, l, r, n)$	PRE-REC-1	$S4 \vdash H(r, p, t)$
(3) $H_1(l, p, t) \Rightarrow H(l, x, lm) @ (x \rightarrow \text{tree}(p, l, r, n) \wedge r \neq \text{NULL})$	PRE-REC-2	$S5 \vdash H(l, p, lm)$
(4) $H_1(l, p, t) * H_r(r, p, t) * x \rightarrow \text{tree}(p, l, r, t) \wedge r = \text{NULL} \wedge \text{res} = x \Rightarrow G(x, p, \text{res}, t)$	POST-1	$S6 \vdash G(x, p, \text{res}, t)$
(5) $H_n(n, p, t) * x \rightarrow \text{tree}(p, l, r, n) * G(r, x, lm, t) * G(l, x, res, lm) \wedge r \neq \text{NULL} \Rightarrow G(x, p, \text{res}, t)$	POST-2	$S7 \vdash G(x, p, \text{res}, t)$

Pre-Predicate Derivation

Apply [Syn-Base] on assumption (4)

- (4a) $\text{res} \rightarrow \text{tree}(p, l, r, t) * H_1(l, p, t) \wedge r = \text{NULL} \wedge \text{res} = x \Rightarrow G(x, p, \text{res}, t)$
(4b) $H_r(r, p, t) \wedge r = \text{NULL} \Rightarrow \text{emp}$
(4c) $H_1(l, p, t) \Rightarrow H_1^i(l, p, t) @ (\text{res} \rightarrow \text{tree}(p, l, r, t) \wedge r = \text{NULL})$
(4d) $H_1^i(l, p, t) \Rightarrow \top$

Apply [Syn-Case], [Syn-Group-Pre], [Syn-Pre-Def]

Synthesized Predicates	Assumptions
$H(x, p, t) \equiv x \rightarrow \text{tree}(x_p, l, r, n) * H_p(x_p, p, t) * H_1(l, p, t) * H_r(r, p, t) * H_n(n, p, t)$	(1)
$H_r(r, p, t) \equiv H(r, x, t) \wedge r \neq \text{NULL} @ x \rightarrow \text{tree}(p, l, r, n) \vee \text{emp} \wedge r = \text{NULL}$	(2), (4b)
$H_1(l, p, t) \equiv H(l, x, lm) @ x \rightarrow \text{tree}(p, l, r, n) \wedge r \neq \text{NULL} \vee H_1^i(l, p, t) @ x \rightarrow \text{tree}(p, l, r, n) \wedge r = \text{NULL}$	(3), (4c)
$H_1^i(l, p, t) \equiv \top$	(4d)

Apply [Syn-Inline]

$$H(x, p, t) \equiv x \rightarrow \text{tree}(x_p, l, r, x_n) * H(l, x, lm) * H(r, x, t) * H_p(x_p, p, t) * H_n(x_n, p, t) \wedge r \neq \text{NULL} \vee x \rightarrow \text{tree}(x_p, l, r, x_n) * H_1^i(l, x, t) * H_p(x_p, p, t) * H_n(x_n, p, t) \wedge r = \text{NULL}$$

Post-Predicate Derivation

Apply [Syn-Group-Post] and [Syn-Post-Def]

Synthesized Predicates	Assumptions
$G(x, p, \text{res}, t) \equiv x \rightarrow \text{tree}(p, l, r, t) * H_1(l, x_h, t_h) \wedge \text{res} = x \wedge r = \text{NULL}$	(4a), (5)
$\vee x \rightarrow \text{tree}(p, l, r, n) * G(r, x, lm, t) * G(l, x, res, lm) * H_n(n, x_h, t_h) \wedge r \neq \text{NULL}$	(4a), (5)

Apply [Syn-Inline]

$$G(x, p, \text{res}, t) \equiv x \rightarrow \text{tree}(p, l, r, t) * H_1^i(l, x_h, t_h) \wedge \text{res} = x \wedge r = \text{NULL} \vee x \rightarrow \text{tree}(p, l, r, n) * G(r, x, lm, t) * G(l, x, res, lm) * H_n(n, x_h, t_h) \wedge r \neq \text{NULL}$$

Detecting and Eliminating Dangling Predicates

$$H(x, p, t) \equiv x \rightarrow \text{tree}(D_p, D_l, r, D_n) \wedge r = \text{NULL} \vee x \rightarrow \text{tree}(D_p, l, r, D_n) * H(l, x, lm) * H(r, x, t) \wedge r \neq \text{NULL} \\ G(x, p, \text{res}, t) \equiv x \rightarrow \text{tree}(p, D_l, r, t) \wedge \text{res} = x \wedge r = \text{NULL} \vee x \rightarrow \text{tree}(p, l, r, D_n) * G(l, x, res, lm) * G(r, x, lm, t) \wedge r \neq \text{NULL}$$

Eliminating Useless Parameters

$$H(x, p, t) \equiv H_f(x) \\ H_f(x) \equiv x \rightarrow \text{tree}(D_p, D_l, r, D_n) \wedge r = \text{NULL} \vee x \rightarrow \text{tree}(D_p, l, r, D_n) * H_f(l) * H_f(r) \wedge r \neq \text{NULL}$$

Implementation and Experiments

Example	w/o norm.		w/ norm.		Veri.
	size	Syn.	size	Syn.	
SLL (delete)	9	0.23	5	0.23	0.2
SLL (reverse)	20	0.2	12	0.23	0.18
SLL (insert)	13	0.21	11	0.21	0.21
SLL (setTail)	7	0.18	2	0.19	0.18
SLL (get-last)	20	0.24	15	0.24	0.22
SLL-sorted (check)	8	0.26	2	0.27	0.23
SLL (bubblesort)	13	0.26	9	0.29	0.31
SLL (insertsort)	15	0.26	11	0.26	0.25
SLL (zip)	12	0.31	2	0.31	0.36
SLL-zip-leq	10	0.3	2	0.3	0.32
SLL + head (check)	9	0.23	2	0.25	0.2
SLL + tail (check)	9	0.25	2	0.26	0.23
skip-list ₂ (check)	11	0.3	6	0.29	0.27
skip-list ₃ (check)	17	0.45	3	0.46	0.45
SLL of 0/1 SLLs	8	0.24	8	0.24	0.25
CSLL (check)	8	0.23	2	0.2	0.22

Example	w/o norm.		w/ norm.		Veri.
	size	Syn.	size	Syn.	
CSLL (traverse)	8	0.23	2	0.24	0.33
CSLL of CSLLs (check)	18	0.31	2	0.3	0.31
SLL2DLL	8	0.19	2	0.18	0.19
DLL (check)	8	0.2	2	0.18	0.2
DLL (append)	23	0.18	8	0.16	0.19
CDLL (check)	9	0.25	7	0.24	0.23
CDLL of 5CSLLs	29	0.69	20	0.74	118
CDLL of CSLLs ₂	33	0.44	22	0.41	0.51
tree (search)	11	0.25	2	0.24	0.24
tree-parent (traverse)	14	0.22	14	0.22	0.27
rose-tree (check)	9	0.22	7	0.24	0.23
swl (traverse)	19	0.39	17	0.34	1
mcf (check)	28	0.31	28	0.31	0.26
tll (traverse)	18	0.19	14	0.22	0.23
tll (check)	39	0.21	32	0.21	0.29
tll-parent (check)	19	0.24	13	0.26	0.29

Implementation:

- CIL infrastructure for C programs.
- Omega and Z3 to discharge numerical proof obligations

Experimental results:

- synthesis time < 1s (Syn. column)
- normalization (w/ norm column) reduces 40% (288/482) the size of synthesized predicates with an overhead of 1% time.

More experiment on Glib library:

	LOC	#Proc	#Loop	#/√	Syn. (second)
glist.c	863	44	19	59	3.45
glist.c	957	29	19	43	6.41
gtree.c	1334	36	14	43	5.26
gnode.c	1131	37	25	55	9.17

- gtree: balanced binary tree
 - gnode: N-ary tree
- infer specifications that guarantee memory safety for 90% of procedures & loops.